

WHAT IS CLAIMED IS:

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1. A shadow rendering method for use in a computer system, the method comprising the steps of:

providing observer data of a simulated multi-dimensional scene;

providing lighting data associated with a plurality of simulated light sources arranged to illuminate said scene, said lighting data including light image data;

for each of said plurality of light sources, comparing at least a portion of said observer data with at least a portion of said lighting data to determine if a modeled point within said scene is illuminated by said light source and storing at least a portion of said light image data associated with said point and said light source in a light accumulation buffer; and then

combining at least a portion of said light accumulation buffer with said observer data; and

displaying resulting image data to a computer screen.

2. The method as recited in Claim 1, wherein said observer data includes observed color data and observed depth

3 data associated with a plurality of modeled polygons within
4 said scene as rendered from an observer's perspective.

1 3. The method as recited in Claim 2, wherein said
2 plurality of modeled polygons within said scene are associated
3 with at least one pixel on said computer screen, such that
4 said observed color data includes an observed red-green-blue
5 value for said pixel and said observed depth data includes an
6 observed z-buffer value for said pixel.

1 4. The method as recited in Claim 2, wherein said
2 lighting data includes source color data associated with at
3 least one of said light sources and source depth data
4 associated with said plurality of modeled polygons within said
5 scene as rendered from a plurality of different light source's
6 perspectives.

1 5. The method as recited in Claim 4, wherein said
2 plurality of modeled polygons within said scene are associated
3 with at least one pixel on said computer screen, such that
4 said source color data includes a source red-green-blue value
5 for said pixel and said source depth data includes a source z-
6 buffer value for said pixel.

10010776-120601

10010776-120604

1 6. The method as recited in Claim 4, wherein the step
2 of comparing at least a portion of said observer data with at
3 least a portion of said lighting data to determine if a
4 modeled point within said scene is illuminated by said light
5 source further includes comparing at least a portion of said
6 observed depth data with at least a portion of said source
7 depth data to determine if said modeled point is illuminated
8 by said light source.

1 7. The method as recited in Claim 6, wherein the step
2 of comparing at least a portion of said observed depth data
3 with at least a portion of said source depth data to determine
4 if said modeled point is illuminated by said light source
5 further includes converting at least a portion of said
6 observed depth data from said observer's perspective to at
7 least one of said plurality of different light source's
8 perspectives, before comparing said observed depth data with
9 said source depth data.

1 8. The method as recited in Claim 7, wherein the step
2 of converting at least a portion of said observed depth data
3 from said observer's perspective to at least one of said

4 plurality of different light source's perspectives further
5 includes using a precalculated matrix transformation look-up
6 table for at least one of said plurality of light sources,
7 when said light source has a fixed perspective of said scene.

1 9. The method as recited in Claim 4, wherein at least
2 a portion of said source color data is selectively controlled
3 source color data that can be changed over a period of time
4 during which at least the step of displaying resulting image
5 data to said computer screen is repeated a plurality of times.

1 10. The method as recited in Claim 9, wherein said
2 controlled source color data includes data selected from a set
3 comprising motion picture data, video data, animation data,
4 and computer graphics data.

1 11. An arrangement configured to render shadows in a
2 simulated multi-dimensional scene, the arrangement comprising:
3 a display screen configured to display image data;
4 memory for storing data including observer data
5 associated with a simulated multi-dimensional scene, and
6 lighting data associated with a plurality of simulated light
7 sources arranged to illuminate said scene, said lighting data

10010776-120601

8 including light image data, said memory further including a
9 light accumulation buffer portion and a frame buffer portion;
10 at least one processor coupled to said memory and said
11 display screen and operatively configured to, for each of said
12 plurality of light sources, compare at least a portion of said
13 observer data with at least a portion of said lighting data to
14 determine if a modeled point within said scene is illuminated
15 by said light source and storing at least a portion of said
16 light image data associated with said point and said light
17 source in said light accumulation buffer, then combining at
18 least a portion of said light accumulation buffer with said
19 observer data, and displaying resulting image data in said
20 frame buffer, and outputting at least a portion of said image
21 data in said frame buffer to said display screen.

1 12. The arrangement as recited in Claim 11, wherein said
2 observer data includes observed color data and observed depth
3 data associated with a plurality of modeled polygons within
4 said scene as rendered from an observer's perspective.

1 13. The arrangement as recited in Claim 12, wherein said
2 plurality of modeled polygons within said scene are associated
3 with at least one pixel on said display screen, such that said

4 observed color data includes an observed red-green-blue value
5 for said pixel and said observed depth data includes a
6 observed z-buffer value for said pixel..

1 14. The arrangement as recited in Claim 12, wherein said
2 lighting data includes source color data associated with at
3 least one of said light sources and source depth data
4 associated with said plurality of modeled polygons within said
5 scene as rendered from a plurality of different light source's
6 perspectives.

1 15. The arrangement as recited in Claim 14, wherein said
2 plurality of modeled polygons within said scene are associated
3 with at least one pixel on said display screen, such that said
4 source color data includes a source red-green-blue value for
5 said pixel and said source depth data includes a source z-
6 buffer value for said pixel.

1 16. The arrangement as recited in Claim 14, wherein said
2 processor is further configured to compare at least a portion
3 of said observed depth data with at least a portion of said
4 source depth data to determine if said modeled point is
5 illuminated by said light source.

1 17. The arrangement as recited in Claim 16, wherein said
2 processor is further configured to convert at least a portion
3 of said observed depth data from said observer's perspective
4 to at least one of said plurality of different light source's
5 perspectives, before comparing said observed depth data with
6 said source depth data.

1 18. The arrangement as recited in Claim 17, wherein said
2 memory further includes at least one precalculated matrix
3 transformation table associated with at least one of said
4 plurality of light sources, and said processor is further
5 configured to use said precalculated matrix transformation
6 look-up table when said light source is simulated as having a
7 fixed perspective of said scene.

1 19. The arrangement as recited in Claim 14, wherein said
2 processor is further configured to selectively control at
3 least a portion of said source color data over a period of
4 time.

1 20. The arrangement as recited in Claim 19, wherein said
2 controlled source color data includes data selected from a set

10010776-120601

3 comprising motion picture data, video data, animation data,
4 and computer graphics data.

1 21. A method for simulating light falling on a modeled
2 object in a computer generated multi-dimensional graphics
3 simulation, the method comprising the steps of:

4 for a simulated camera, rendering a camera view of at
5 least one modeled object that is at least partially optically
6 opaque, to produce a camera depth array comprising camera
7 depth data values and a corresponding camera image array
8 comprising camera image data values;

9 for a first simulated light, rendering a first light view
10 of said modeled object to produce a first light depth array
11 comprising first light depth data values and a corresponding
12 first light image array comprising first light image data
13 values;

14 transforming at least a portion of said camera depth data
15 values to said first light view, thereby generating a first
16 transformed camera array comprising first transformed camera
17 depth data values;

18 for each data value therein, comparing said first light
19 depth array to said first transformed camera array to
20 determine if said data value in said first light depth array

21 is closer to said first simulated light, and if so, adding a
22 corresponding data value from said first light image array to
23 a light accumulation array comprising light accumulation data
24 values; and

25 for each data value therein, multiplying said camera
26 image array by a corresponding data value from said light
27 accumulation array to produce a lighted camera image array
28 comprising lighted camera image values.

1 22. The method as recited in Claim 21, wherein, prior to
2 the step of multiplying said camera image array by a
3 corresponding data value from said light accumulation array to
4 produce a lighted camera image array, the method further
5 includes the steps of:

6 for a second simulated light, rendering a second light
7 view of said modeled object to produce a second light depth
8 array comprising second light depth data values and a
9 corresponding second light image array comprising second light
10 image data values;

11 transforming at least a portion of said camera depth data
12 values to said second light view, thereby generating a second
13 transformed camera array comprising second transformed camera
14 depth data values; and

10010776.120601

15 for each data value therein, comparing said second light
16 depth array to said second transformed camera array to
17 determine if said data value in said second light depth array
18 is closer to said second simulated light, and if so, adding a
19 corresponding data value from said second light image array to
20 said light accumulation array.

1 23. The method as recited in Claim 21, wherein each of
2 said camera depth values includes z-buffer data associated
3 with a different pixel selected from a plurality of pixels on
4 a computer display screen.

1 24. The method as recited in Claim 23, wherein each of
2 said first light depth values includes z-buffer data
3 associated with a different pixel selected from a plurality of
4 pixels on a computer display screen.

1 25. The method as recited in Claim 21, wherein each of
2 said camera depth values includes z-buffer data associated
3 with a different set of pixels selected from a plurality of
4 pixels on a computer display screen.

100010776-120601

1 26. The method as recited in Claim 25, wherein each of
2 said first light depth values includes z-buffer data
3 associated with a different set of pixels selected from a
4 plurality of pixels on a computer display screen.

1 27. The method as recited in Claim 21, wherein said
2 camera image data and said first light image data each include
3 color data associated with at least one pixel on a computer
4 screen.

1 28. The method as recited in Claim 21, further
2 comprising the steps of:
3 repeating the steps recited in Claim 21 at a frame rate;
4 and
5 sequentially displaying a plurality of frames of data on
6 a computer screen at said frame rate, wherein subsequent
7 frames of data include subsequently processed lighted camera
8 image data, and wherein said step of rendering said first
9 light view further comprises dynamically changing at least one
10 of said first light image data values between said subsequent
11 frames of data.

10010776, 120601

1 29. The method as recited in Claim 28 wherein at least
2 a portion of said first light image data values represent
3 dynamically changing color data selected from a set comprising
4 motion picture data, video data, animation data, and computer
5 graphics data.

1 30. The method as recited in Claim 28, wherein said
2 frame rate is at least about 25 frames per second.

1 31. The method as recited in Claim 21, wherein the step
2 of transforming at least a portion of said camera depth data
3 values to said first light view further includes the step of
4 transforming said camera depth array from a camera coordinate
5 system to a corresponding first light coordinate system.

1 32. The method as recited in Claim 31, wherein the step
2 of transforming said camera depth array from a camera
3 coordinate system to a corresponding first light coordinate
4 system further includes the step of using a precalculated
5 transformation table to transform directly from said camera
6 coordinate system to said corresponding first light coordinate
7 system.

10010776-120601

1 33. A computer-readable medium carrying at least one set
2 of computer instructions configured to cause a computer to
3 operatively simulate light falling on a modeled object in a
4 computer generated multi-dimensional graphics simulation by
5 performing operations comprising:
6 a) rendering an observer view of at least a portion of
7 a spatially modeled object as a plurality of observed depth
8 values and observed image values;
9 b) rendering a source view of at least a portion of
10 said modeled object as a plurality of source depth values and
11 a plurality of source image values;
12 c) transforming at least a portion of said observed
13 depth values to said source view;
14 d) modifying at least one image accumulation value with
15 one of said observed image values if said corresponding
16 transformed observer value is equal to a comparable one of
17 said source depth values;
18 e) multiplying said one of said observed image values
19 by said at least one image accumulation value to produce at
20 least one pixel value; and
21 f) displaying said pixel value on a computer screen .

10010776-120601

1 34. The computer-readable medium as recited in Claim 33,
2 further configured to cause the computer to perform the
3 further step of:

4 g) following step d), repeating steps b) through d) for
5 at least one additional source view.

1 35. The computer-readable medium as recited in Claim 34,
2 further configured to cause the computer to perform the
3 further steps of:

4 h) repeating steps a) through g) a frame rate; and
5 wherein step f) further includes sequentially displaying
6 a plurality of pixels as frames of data on said computer
7 screen at said frame rate, and said step of rendering said
8 source view further includes changing at least one of said
9 source image values between said subsequent frames of data.

1 36. The computer-readable medium as recited in Claim 35
2 wherein at least a portion of said source image values
3 represent color data selected from a set comprising motion
4 picture data, video data, animation data, and computer
5 graphics data.

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1 37. The computer-readable medium as recited in Claim 35,
2 wherein step c) further includes transforming at least a
3 portion of said observed depth values from an observer
4 coordinate system to a corresponding source coordinate system.

1 38. The computer-readable medium as recited in Claim 37,
2 wherein the step of transforming at least a portion of said
3 observed depth values from an observer coordinate system to a
4 corresponding source coordinate system further includes using
5 a precalculated transformation table to transform directly
6 from said observer coordinate system to said corresponding
7 source coordinate system.

1 39. A computer-readable medium carrying at least one set
2 of computer instructions configured to cause at least one
3 processor within a computer system to operatively render
4 simulated shadows in a multi-dimensional simulated scene by
5 performing the steps of:
6 providing observer data of a simulated multi-dimensional
7 scene;
8 providing lighting data associated with a plurality of
9 simulated light sources arranged to illuminate said scene,
10 said lighting data including light image data;

11 for each of said plurality of light sources, comparing at
12 least a portion of said observer data with at least a portion
13 of said lighting data to determine if a modeled point within
14 said scene is illuminated by said light source and storing at
15 least a portion of said light image data associated with said
16 point and said light source in a light accumulation buffer;
17 and then

18 combining at least a portion of said light accumulation
19 buffer with said observer data; and

20 displaying resulting image data to a computer screen.

1 40. The computer-readable medium as recited in Claim 39,
2 wherein said observer data includes observed color data and
3 observed depth data associated with a plurality of modeled
4 polygons within said scene as rendered from an observer's
5 perspective.

1 41. The computer-readable medium as recited in Claim 40,
2 wherein said plurality of modeled polygons within said scene
3 are associated with at least one pixel on said computer
4 screen, such that said observed color data includes an
5 observed red-green-blue value for said pixel and said

6 observed depth data includes a observed z-buffer value for
7 said pixel..

1 42. The computer-readable medium as recited in Claim 40,
2 wherein said lighting data includes source color data
3 associated with at least one of said light sources and source
4 depth data associated with said plurality of modeled polygons
5 within said scene as rendered from a plurality of different
6 light source's perspectives.

1 43. The computer-readable medium as recited in Claim 42,
2 wherein said plurality of modeled polygons within said scene
3 are associated with at least one pixel on said computer
4 screen, such that said source color data includes a source
5 red-green-blue value for said pixel and said source depth data
6 includes a source z-buffer value for said pixel.

1 44. The computer-readable medium as recited in Claim 42,
2 wherein the step of comparing at least a portion of said
3 observer data with at least a portion of said lighting data to
4 determine if a modeled point within said scene is illuminated
5 by said light source further includes comparing at least a
6 portion of said observed depth data with at least a portion of

7 said source depth data to determine if said modeled point is
8 illuminated by said light source.

1 45. The computer-readable medium as recited in Claim 44,
2 wherein the step of comparing at least a portion of said
3 observed depth data with at least a portion of said source
4 depth data to determine if said modeled point is illuminated
5 by said light source further includes converting at least a
6 portion of said observed depth data from said observer's
7 perspective to at least one of said plurality of different
8 light source's perspectives, before comparing said observed
9 depth data with said source depth data.

1 46. The computer-readable medium as recited in Claim 45,
2 wherein the step of converting at least a portion of said
3 observed depth data from said observer's perspective to at
4 least one of said plurality of different light source's
5 perspectives further includes using a precalculated matrix
6 transformation look-up table for at least one of said
7 plurality of light sources, when said light source has a fixed
8 perspective of said scene.

1 47. The computer-readable medium as recited in Claim 42,
2 wherein at least a portion of said source color data is
3 selectively controlled source color data that can be changed
4 over a period of time during which at least the step of
5 displaying resulting image data to said computer screen is
6 repeated a plurality of times.

1 48. The computer-readable medium as recited in Claim 47,
2 wherein said controlled source color data includes data
3 selected from a set comprising motion picture data, video
4 data, animation data, and computer graphics data.

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